

INTERNATIONAL CONFERENCE

OPTIMIZATION AND CONTROL

**Dedicated to B.T. POLYAK's 70th anniversary**

Moscow May 19-20, 2005

**On a Variational Problem Associated with  
a Model of Welfare Economics**

A.D. Ioffe,

Technion, Haifa,

ISRAEL

## **Plan of the talk:**

1. Statement of the problem
2. A brief account of the theory
3. The model. Two main theorems of welfare economics
4. Variational formulation.
5. Preference mapping vs. utility function
6. Generalized equilibria and unjust distributions

## 1. The variational problem

$$(VP) \quad \begin{aligned} & \text{minimize} \quad \int_T f(t, u(t)) d\mu \\ & \text{s.t.} \quad \int_T u(t) d\mu = a \end{aligned}$$

Here:  $(T, \Sigma, \mu)$  is a measure space;

$f(t, x)$  a normal integrand (extended-real-valued) on  $T \times \mathbb{R}^n$ .

## 1. The variational problem

$$(VP) \quad \begin{aligned} & \text{minimize} \quad \int_T f(t, u(t)) d\mu \\ & \text{s.t.} \quad \int_T u(t) d\mu = a \end{aligned}$$

Here:  $(T, \Sigma, \mu)$  is a measure space;  
 $f(t, x)$  a normal integrand (extended-real-valued) on  $T \times \mathbb{R}^n$ .

Scope and applications:

(a) Optimal control of linear systems:

$$\dot{x} = A(t)x + b(t, u), \quad u \in U(t);$$

## 1. The variational problem

$$(VP) \quad \begin{aligned} & \text{minimize} \quad \int_T f(t, u(t)) d\mu \\ & \text{s.t.} \quad \int_T u(t) d\mu = a \end{aligned}$$

Here:  $(T, \Sigma, \mu)$  is a measure space;  
 $f(t, x)$  a normal integrand (extended-real-valued) on  $T \times \mathbb{R}^n$ .

Scope and applications:

(a) Optimal control of linear systems:

$$\dot{x} = A(t)x + b(t, u), \quad u \in U(t);$$

(b) Mathematical economics  
(Yaari (1964), Aumann-Perles (1965));

## 1. The variational problem

$$(VP) \quad \begin{aligned} & \text{minimize} \quad \int_T f(t, u(t)) d\mu \\ & \text{s.t.} \quad \int_T u(t) d\mu = a \end{aligned}$$

Here:  $(T, \Sigma, \mu)$  is a measure space;  
 $f(t, x)$  a normal integrand (extended-real-valued) on  $T \times \mathbb{R}^n$ .

Scope and applications:

(a) Optimal control of linear systems:

$$\dot{x} = A(t)x + b(t, u), \quad u \in U(t);$$

(b) Mathematical economics

(Yaari (1964), Aumann-Perles (1965));

(c) PDE's with radially symmetric coefficients

(Cellina-Perrotta (1994), Crasta (2000))

## 1. The variational problem

$$(VP) \quad \begin{aligned} & \text{minimize} \quad \int_T f(t, u(t)) d\mu \\ & \text{s.t.} \quad \int_T u(t) d\mu = a \end{aligned}$$

Here:  $(T, \Sigma, \mu)$  is a measure space;  
 $f(t, x)$  a normal integrand (extended-real-valued) on  $T \times \mathbb{R}^n$ .

Scope and applications:

(a) Optimal control of linear systems

$$\dot{x} = A(t)x + b(t, u), \quad u \in U(t);$$

(b) Mathematical economics

(Yaari (1964), Aumann-Perles (1965));

(c) PDE's with radially symmetric coefficients

(Cellina-Perrotta (1994), Crasta (2000))

(d) Lipschitz regularity of autonomous variational problems

(Ambrosio-Ascenzi-Buttazzo (1989)).

(Also Berliocchi-Lasri (1973), Artstein (1974), Fusco-Marcellini-Ornelas (1998), Balder (2000) and many others.)

## 2. Theory (Ioffe-Tikhomirov (1969))

Let  $S(x)$  denote the value function of the problem:

$$S(x) = \inf \left\{ \int_T f(t, x(t)) d\mu : \int_T x(t) d\mu = x \right\}.$$

Then

$$S^*(p) = \int_T f^*(t, p) d\mu;$$

(A) Regular case

**Theorem 1.** *Assume that  $f(t, \cdot)$  is convex whenever  $t$  is an atom. If  $a \in \partial S(\bar{p})$  for some  $\bar{p} \in \text{int}(\text{dom } S^*)$ , then (VP) has a solution, and  $\bar{x}(t)$  is a solution of (VP) if and only if (it is admissible in the problem and)*

$$f(t, \bar{x}(t)) + f^*(t, \bar{p}) = \bar{p} \cdot \bar{x}(t) \quad \text{a.e..}$$

In other words,  $\bar{x}(t)$  maximizes  $x \rightarrow f(t, x) - \bar{p} \cdot x$  for almost every  $t$ .



## 2. Theory (Ioffe-Tikhomirov (1969))

Let  $S(x)$  denote the value function of the problem:

$$S(a) = \inf \left\{ \int_T f(t, x(t)) d\mu : \int_T x(t) d\mu = x \right\}.$$

Then

$$S^*(p) = \int_T f^*(t, p) d\mu;$$

### (A) Regular case

**Theorem 1.** *Assume that  $f(t, \cdot)$  is convex whenever  $t$  is an atom. If  $a \in \partial S(\bar{p})$  for some  $\bar{p} \in \text{int}(\text{dom } S^*)$ , then (VP) has a solution, and  $\bar{x}(t)$  is a solution of (VP) if and only if (it is admissible in the problem and)*

$$f(t, \bar{x}(t)) + f^*(t, \bar{p}) = \bar{p} \cdot \bar{x}(t) \quad \text{a.e.}$$

### (B) General case

ASSUMPTION:  $T$  is a compact metric space and  $\mu$  is a regular Borel measure on  $T$ . (Not very restrictive in view of Rohlin's characterization of Lebesgue spaces!)

**Definition.**  $t$  is a  $p$ -critical point ( $p \in \text{dom } S^*$ ) if

$$p \notin \text{int}(\text{dom } \int_U f^*(t, p) d\mu), \quad \forall \text{ nbd } U \ni t.$$

Notation  $t \in T(p)$ .

(B) General case

ASSUMPTION:  $T$  is a compact metric space and  $\mu$  is a regular Borel measure on  $T$ . (Not very restrictive in view of Rohlin's characterization of Lebesgue spaces!)

**Definition.**  $t$  is a  $p$ -critical point ( $p \in \text{dom } S^*$ ) if

$$p \notin \text{int} \left( \text{dom} \int_{B(t,\varepsilon)} f^*(t,p) d\mu \right), \forall \varepsilon > 0.$$

Notation:  $t \in T(p)$ .

For a  $t \in T(p)$  set

$$Q(t) = \lim_{\varepsilon \rightarrow 0} \left( \text{dom} \int_{B(t,\varepsilon)} f^*(t, \cdot) d\mu \right).$$

*The following is a relaxation of (VP) in the weak\* topology of the space of  $\mathbb{R}^n$ -valued Radon measures on  $T$  whose singular parts consists of at most  $n$  atoms in  $T(p)$  for a certain  $p \in \text{dom } S^*$ :*

$$(GP) \quad \left\{ \begin{array}{l} \text{minimize} \quad \int_T f(t, x(t)) d\mu + \sum_{i=1}^k s(Q(t_i), w_i) \\ \text{s.t.} \quad \int_T (x(t) d\mu + \sum_{i=1}^k w_i d\varepsilon_{t_i}) = a, \end{array} \right.$$

(Here  $s(P, \cdot)$  stands for the support function of  $P$ ,  $t_i \in T(p)$  and  $\varepsilon_t$  is the unit jump at  $t$ .)

**Theorem 2.** *Suppose that  $\text{int}(\text{dom } S^*) \neq \emptyset$ . If  $a \in \partial S^*(\bar{p})$  and  $\bar{p}$  does not belong to the interior, then (GP) has a solution, and  $y = (x(\cdot), w_1, \dots, w_k, t_1, \dots, t_k)$  is a solution of (GP) if and only if (it is admissible in (GP) and)*

$$f(t, x(t)) + f^*(t, \bar{p}) = \bar{p} \cdot x(t) \quad \text{a.e.}$$

*and*

$$\bar{p} \cdot w_i = s(Q(t_i), w_i), \quad \forall i = 1, \dots, k.$$

### 3. A model of welfare economics with a measure space of agents (Hildenbrand (1969))

GIVEN:

a **measure space of agents**  $(T, \Sigma, \mu)$  which is a disjoint union of two parts, the **consumer part**  $T_c$  and the **production part**  $T_p$ ;

an **allocation map** which is a set-valued mapping  $X(t)$  from  $T$  into  $\mathbb{R}^n$ ;

a **preference map** which is a set-valued mapping  $P(t, x)$  from the restriction of  $\text{Graph}X$  to  $T_c$  into  $\mathbb{R}^n$  such that  $P(t, x) \subset X(t)$  for all  $x \in X(t)$  almost everywhere on  $T_c$ ,

an **initial endowment**  $a$ .

### 3. A model of welfare economics with a measure space of agents (Hildenbrand (1969))

GIVEN:

a **measure space of agents**  $(T, \Sigma, \mu)$  which is a disjoint union of two parts, the *consumer part*  $T_c$  and the *production part*  $T_p$ ;

an **allocation map** which is a set-valued mapping  $X(t)$  from  $T$  into  $\mathbb{R}^n$ ;

a **preference map** which is a set-valued mapping  $P(t, x)$  from the restriction of  $\text{Graph}X$  to  $T_c$  into  $\mathbb{R}^n$  such that  $P(t, x) \subset X(t)$  for all  $x \in X(t)$  almost everywhere on  $T_c$ ,

an **initial endowment**  $a$ .

ASSUMPTIONS:

(**A<sub>1</sub>**) there is a normal integrand  $\varphi(t, x)$  on  $T_c \times \mathbb{R}^n$  which assumes finite values on the graph of  $X(\cdot)$  and which **represents the preference map** in the sense that for any  $x \in X(t)$  the preference set, if nonempty, is defined by

$$P(t, x) = \{u \in X(t) : \varphi(t, u) < \varphi(t, x)\}.$$

(**A<sub>2</sub>**) for any  $(t, x) \in \text{Graph}X$  either  $P(t, x) = \emptyset$  or

$$\{u \in X(t) : \varphi(t, u) \leq \varphi(t, x)\} = \overline{P(t, x)}.$$

(Here the bar denotes the closure.)

We shall denote by  $M(t)$  the set of **satiation (full satisfaction) consumptions** of consumer  $t$ . This is the set of  $x$  at which  $P(t, x) = \emptyset$ . For  $x \in M(t)$  we set by definition

$$\overline{P(t, x)} = M(t).$$

(**A<sub>3</sub>**) the restriction of  $\mu$  to  $T_c$  is non-atomic; if  $t \in T_p$  is an atom, then  $X(t)$  is a convex set.

## Some definitions:

$x(t)$  a **feasible allocation** if

$$x(t) \in X(t) \quad \text{a.e.}; \quad \int_{T_c} x(t) d\mu = a + \int_{T_p} x(t) d\mu.$$

A feasible allocation  $x(t)$  is a **Pareto optimum in the model** if for any other feasible allocation  $u(t)$

- either  $x(t) \in \overline{P(t, u(t))}$  a.e. on  $T_c$ ,
- or  $x(t) \in P(t, u(t))$  on a set of positive measure;

(that is, if either no consumer would prefer  $u(t)$  to  $x(t)$  or a solid fraction of consumers would prefer  $x(t)$  to  $u(t)$ ),

or, in terms of the utility function, if

- either  $\varphi(t, u(t)) \geq \varphi(t, x(t))$  a.e. on  $T_c$ ,
- or  $\varphi(t, u(t)) > \varphi(t, x(t))$  on a subset of  $T_c$  of positive measure.

Given a  $p \in \mathbb{R}^n$ , a feasible allocation  $x(t)$  is a **(pseudo-)equilibrium** with respect to  $p$  if for almost every  $t \in T_c$

$$p \cdot w \geq p \cdot x(t), \quad \forall w \in P(t, x(t))$$

and for almost every  $t \in T_p$

$$p \cdot w \leq p \cdot x(t), \quad \forall w \in X(t).$$

## Two basic questions:

- whether there is a Pareto optimum in the model;
- whether there is an equilibrium in the model

## Variational formulation

Set

$$f(t, x) = f_\varphi(t, x) = \begin{cases} \varphi(t, x), & \text{if } t \in T_c, x \in X(t); \\ 0, & \text{if } t \in T_p, x \in -X(t); \\ \infty, & \text{if } t \in T_c, x \notin X(t); \\ \infty, & \text{if } t \in T_p, x \notin -X(t). \end{cases}$$

and consider the problem

$$\begin{aligned} (VP_\varphi) \quad & \text{minimize} && \int_T f(t, y(t)) d\mu, \\ & \text{s.t.} && \int_T y(t) d\mu = a. \end{aligned}$$

## 4. Variational formulation

Set

$$f(t, x) = f_\varphi(t, x) = \begin{cases} \varphi(t, x), & \text{if } t \in T_c, x \in X(t); \\ 0, & \text{if } t \in T_p, x \in -X(t); \\ \infty, & \text{if } t \in T_c, x \notin X(t); \\ \infty, & \text{if } t \in T_p, x \notin -X(t). \end{cases}$$

and consider the problem

$$(VP_\varphi) \quad \begin{aligned} & \text{minimize} && \int_T f(t, y(t)) d\mu, \\ & \text{s.t.} && \int_T y(t) d\mu = a. \end{aligned}$$

**Proposition 3.** *Assume  $(\mathbf{A}_1)$ ,  $(\mathbf{A}_2)$ . If  $\bar{y}(t)$  is a solution of  $(\mathbf{P})$ , then  $\bar{x}(t)$  defined by*

$$\bar{x}(t) = \begin{cases} \bar{y}(t), & \text{if } t \in T_c; \\ -\bar{y}(t), & \text{if } t \in T_p \end{cases}$$

*is a Pareto optimum in the model.*



## 4. Variational formulation

Set

$$f(t, x) = f_\varphi(t, x) = \begin{cases} \varphi(t, x), & \text{if } t \in T_c, x \in X(t); \\ 0, & \text{if } t \in T_p, x \in -X(t); \\ \infty, & \text{if } t \in T_c, x \notin X(t); \\ \infty, & \text{if } t \in T_p, x \notin -X(t). \end{cases}$$

and consider the problem

$$(VP_\varphi) \quad \begin{aligned} & \text{minimize} && \int_T f(t, y(t)) d\mu, \\ & \text{s.t.} && \int_T y(t) d\mu = a. \end{aligned}$$

**Proposition 3.** *Assume  $(\mathbf{A}_1)$ ,  $(\mathbf{A}_2)$ . If  $\bar{y}(t)$  is a solution of  $(\mathbf{P})$ , then  $\bar{x}(t)$  defined by*

$$\bar{x}(t) = \begin{cases} \bar{y}(t), & \text{if } t \in T_c; \\ -\bar{y}(t), & \text{if } t \in T_p \end{cases}$$

*is a Pareto optimum in the model.*

Let as earlier  $S_\varphi(x)$  be the value function of  $(VP_\varphi)$  (with  $x$  replacing  $a$  in the right-hand side of the constraint).

**Proposition 4.** *If there is  $\bar{p} \in \text{intdom } S_\varphi^*$  such that  $a \in \partial S_\varphi^*(\bar{p})$ , then feasible allocation  $\bar{x}(t)$  which is a Pareto optimum and an equilibrium with respect to  $\bar{p}$ .*

(The proof is immediate from Theorem 1 and Proposition 3.)

## 5. Preference map vs. utility functions

**Question:** *assuming that the preference map can be represented by a utility function, which properties of  $X$  and  $P$  may guarantee the existence of a  $\varphi$  for which the basic conditions of the propositions hold? These are:*

- (a) there is a  $\bar{p}$  such that  $a \in \partial S^*(\bar{p})$ ;
- (b) this  $\bar{p}$  belongs to the interior of  $\text{dom } S^*$ .

## 5. Preference map vs. utility functions

**Question:** *assuming that the preference map can be represented by a utility function, which properties of  $X$  and  $P$  may guarantee the existence of a  $\varphi$  for which the basic conditions of the propositions hold? These are:*

- (a) there is a  $\bar{p}$  such that  $a \in \partial S^*(\bar{p})$ ;
- (b) this  $\bar{p}$  belongs to the interior of  $\text{dom } S^*$ .

$$\text{Let } X_c = \int_{T_c} X(t) d\mu \quad \text{and} \quad X_p = \int_{T_p} X(t) d\mu$$

(the sets of possible **total** consumptions and supplies)

A sufficient condition for

(a) *there is a  $\bar{p}$  such that  $\bar{a} \in \partial S^*(\bar{p})$*

to hold:

**Proposition 5.** *Set*

$$W = X_c - X_p.$$

*Then*

(a) *If  $a \notin \text{ri}W$ , then there is a price vector  $p \neq 0$  such that every feasible allocation is a pseudo-equilibrium with respect to  $p$ ;*

(b) *If  $a \in \text{ri}W$ , then for any utility function associated with  $P(t, x)$  there is a price vector  $\bar{p}$  such that  $a \in \partial S_\varphi^*(\bar{p})$  .*

A sufficient conditions for

(b) *the  $\bar{p}$  belongs to the interior of  $\text{dom } S_\varphi^*$*

to hold:

**Proposition 6.** *Assume that*

(i)  *$X(t)$  is integrably bounded on  $T_p$  (that is the set  $X_p$  of possible total supplies is bounded)*

(ii)  *$M(t) \neq \emptyset$  for almost all  $t \in T_c$  and  $\delta_M(t, 0) = \sup\{\|u\| : u \in M(t)\}$  is  $\mu$ -summable on  $T_c$  (that is for almost every consumer there is a "full satisfaction" consumption and the set of total full satisfaction consumptions is bounded)*

(iii) *for all  $x \in X(t)$ , the excess  $r(t, x) < \infty$  of  $P(t, x)$  from  $M(t)$  is finite a.e. on  $T_c$  (that is almost every consumer is "reasonable" in defining preferences)*

*Then there is a normal integrand  $\varphi$  representing  $P(t, x)$  and such that  $\text{dom } S_\varphi^* = \mathbb{R}^n$ .*

**Proposition 7.** *Suppose again that  $X(t)$  is integrably bounded on  $T_p$ . If  $X_c$  does not contain lines (that is no two coalitions of consumers have conflicting preferences), then there is a normal integrand  $\varphi(t, x)$  representing  $P(t, x)$  and such that*

$$\text{int}(\text{dom } S_\varphi^*) \neq \emptyset.$$

## 6. Generalized equilibria and “unjust distributions”

Here we assume that  $T_c$  and  $T_p$  are disjoint metric compact sets.

---

$y = (x(\cdot), w_1, \dots, w_k, t_1, \dots, t_k)$ , ( $k \leq n$ ) is a **generalized allocation** if

(i)  $x(\cdot)$  is an allocation, that is

$$x(t) \in X(t) \quad \text{a.e.}; \quad \int_{T_c} x(t) d\mu = a + \int_{T_p} x(t) d\mu;$$

(ii)  $t_i \in T_c$  and  $s(Q(t_i), w_i) < \infty$ , where

$$Q(t) = \lim_{\varepsilon \rightarrow 0} \left( \text{dom} \int_{B(t, \varepsilon)} f^*(t, \cdot) d\mu \right).$$

A generalized allocation is a **generalized (pseudo-)equilibrium** with respect to  $p$  if

(i)  $x(\cdot)$  is a pseudo-equilibrium, that is for almost every  $t \in T_c$

$$p \cdot w \geq p \cdot x(t), \quad \forall w \in P(t, x(t))$$

and for almost every  $t \in T_p$

$$p \cdot w \leq p \cdot x(t), \quad \forall w \in X(t).$$

(ii)  $p \cdot w_i \geq p \cdot w, \quad \forall w \in Q(t_i), \quad i = 1, \dots, k).$

*(That is: a generalized equilibrium consumption is an “equilibrium distribution” in which arbitrarily small coalitions (around  $t_i$ ) grasp a sizable portion of consumer goods!)*

**Question:** *Do there exist models with “inherent injustice” in which for a certain  $a$  only generalized equilibria appear for any utility function associated with the preference map?*

**Example:** a model of pure consumption, with  $T_c = T = [0, 1/2]$ ,

$$X(t) = \mathbb{R}_+^2 = \{x \in \mathbb{R}^2 : x_i \geq 0\}, \quad \forall t.$$

and  $P(t, x)$  defined by the utility function

$$\varphi(x) = \max\{-2(x_1 - tx_2), -2(x_2 - tx_1), -x_1 + tx_2, -x_2 + tx_1\}.$$

Here

$$P(t, x) = (z(t, x) + K(t)) \cap \mathbb{R}_+^2; \quad \text{where}$$

$$K(t) = \{x \in \mathbb{R}_+^2 : x_1 \geq tx_2; x_2 \geq tx_1\}$$

and

$$z(t, x) = -\frac{1}{1-t} \begin{cases} (\varphi(x), \varphi(x)), & \text{if } \varphi(x) \leq 0 \\ \frac{1}{2}(\varphi(x), \varphi(x)), & \text{if } \varphi(x) \geq 0 \end{cases}$$

In this model “ordinary equilibria” exist only if both components of the initial endowment vector  $a$  are equal

**Open problem:** find general conditions on  $X(t)$  and  $P(t, x)$  which do not exclude unboundedness of preference sets and guarantee that for any initial endowment vector  $a$  there is an “ordinary” equilibrium.