



Optimization and Control

Moscow, May 19-20, 2005

1

Weak Stationarity of Set Systems

Alexander Kruger

Centre of Information and Applied Optimization
School of Information Technology and Mathematical Sciences

University of Ballarat, Australia

a.kruger@ballarat.edu.au



Optimization and Control

2

Moscow, May 19-20, 2005

Outline

- Extremal Set Systems
- Extremality/Stationarity/Regularity
- Dual Criteria



Optimization and Control

2

Moscow, May 19-20, 2005

Outline

- Extremal Set Systems
- Extremality/Stationarity/Regularity
- Dual Criteria
- Metric Inequality
- Boundary Condition
- Regularity of Multifunctions



Optimization and Control

Moscow, May 19-20, 2005

3

Extremal Set Systems



Optimization and Control

Moscow, May 19-20, 2005

3

Extremal Set Systems

Kruger, Mordukhovich, 1980



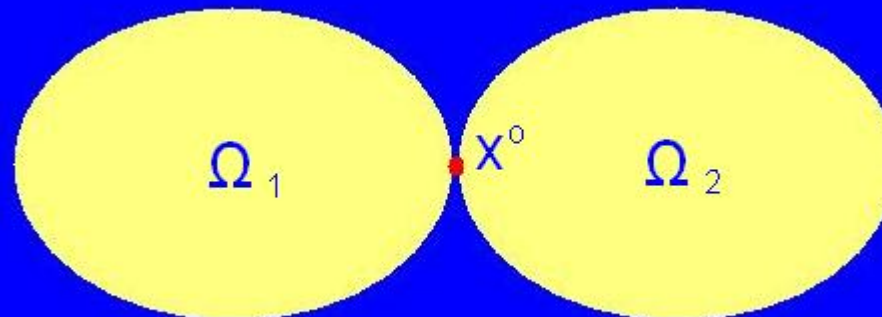
Optimization and Control

3

Moscow, May 19-20, 2005

Extremal Set Systems

Kruger, Mordukhovich, 1980





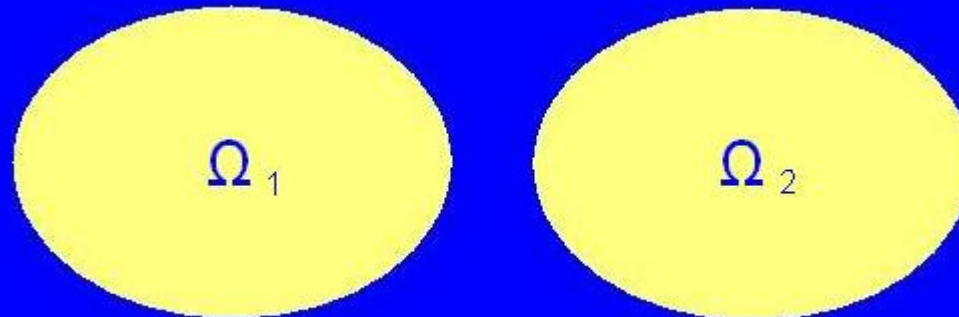
Optimization and Control

3

Moscow, May 19-20, 2005

Extremal Set Systems

Kruger, Mordukhovich, 1980



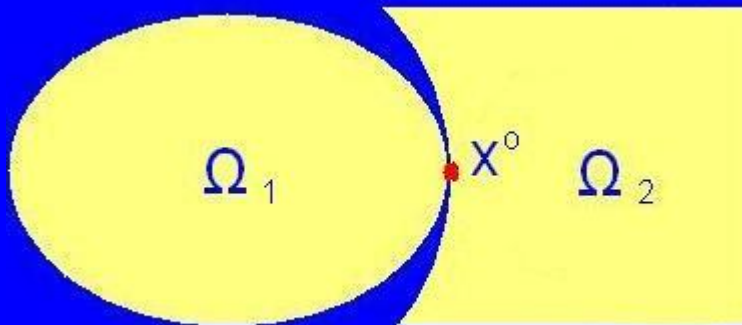


Optimization and Control

Moscow, May 19-20, 2005

4

Extremal Set Systems



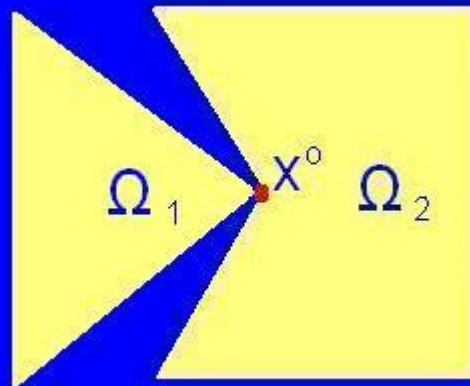
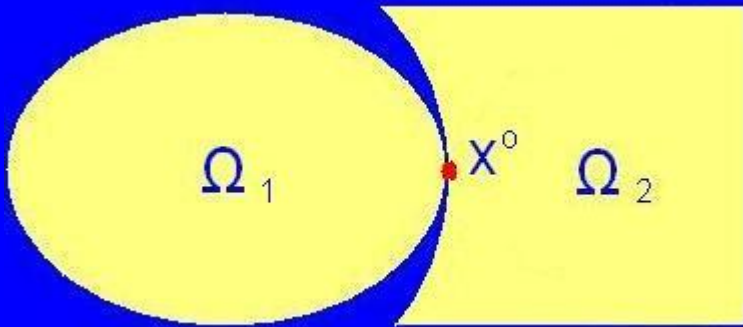


Optimization and Control

4

Moscow, May 19-20, 2005

Extremal Set Systems



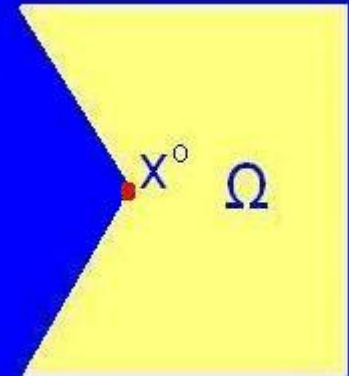
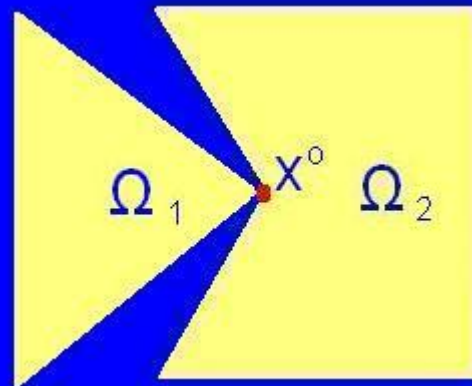
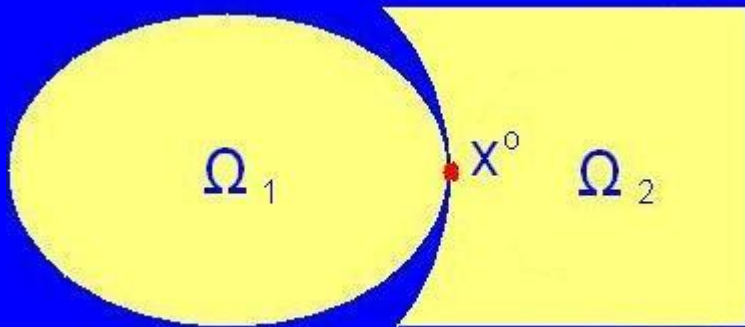


Optimization and Control

Moscow, May 19-20, 2005

4

Extremal Set Systems





Optimization and Control

Moscow, May 19-20, 2005

5

Extremality/Stationarity/Regularity

$$\Omega_1, \Omega_2, \dots, \Omega_n \subset X, x^\circ \in \bigcap_{i=1}^n \Omega_i, \omega_i \in \Omega_i, i = 1, 2, \dots, n$$



Optimization and Control

5

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

$\Omega_1, \Omega_2, \dots, \Omega_n \subset X, x^\circ \in \bigcap_{i=1}^n \Omega_i, \omega_i \in \Omega_i, i = 1, 2, \dots, n$

$\theta_\rho[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n) = \sup \left\{ r \geq 0 : \right.$

$\left. \left(\bigcap_{i=1}^n (\Omega_i - \omega_i - a_i) \right) \cap B_\rho \neq \emptyset, \forall a_i \in B_r \right\}$



Optimization and Control

5

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

$\Omega_1, \Omega_2, \dots, \Omega_n \subset X, x^\circ \in \bigcap_{i=1}^n \Omega_i, \omega_i \in \Omega_i, i = 1, 2, \dots, n$

$\theta_\rho[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n) = \sup \left\{ r \geq 0 : \right.$

$\left. \left(\bigcap_{i=1}^n (\Omega_i - \omega_i - a_i) \right) \cap B_\rho \neq \emptyset, \forall a_i \in B_r \right\}$

$\theta[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n) = \liminf_{\rho \rightarrow +0} \frac{\theta_\rho[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n)}{\rho}$



Optimization and Control

5

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

$\Omega_1, \Omega_2, \dots, \Omega_n \subset X, x^\circ \in \bigcap_{i=1}^n \Omega_i, \omega_i \in \Omega_i, i = 1, 2, \dots, n$

$\theta_\rho[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n) = \sup \left\{ r \geq 0 : \right.$

$\left. \left(\bigcap_{i=1}^n (\Omega_i - \omega_i - a_i) \right) \cap B_\rho \neq \emptyset, \forall a_i \in B_r \right\}$

$\theta[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n) = \liminf_{\rho \rightarrow +0} \frac{\theta_\rho[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n)}{\rho}$

$\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) = \liminf_{\omega_i \xrightarrow{\Omega_i} x^\circ} \theta[\Omega_1, \dots, \Omega_n](\omega_1, \dots, \omega_n)$



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

(1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

- (1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for some $\rho > 0$.



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

- (1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at x° if $\theta[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

- (1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at x° if $\theta[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.
- (4) *weakly stationary* at x° if $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

- (1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at x° if $\theta[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.
- (4) *weakly stationary* at x° if $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.
- (5) *regular* at x° if $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) > 0$.



Optimization and Control

6

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Definition 1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is

- (1) *extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at x° if $\theta_\rho[\Omega_1, \dots, \Omega_n](x^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at x° if $\theta[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.
- (4) *weakly stationary* at x° if $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) = 0$.
- (5) *regular* at x° if $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) > 0$.

$$(1) \Rightarrow (2) \Rightarrow (3) \Rightarrow (4)$$

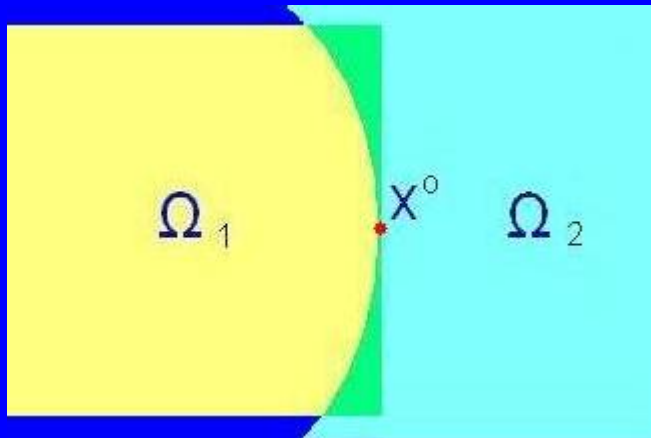


Optimization and Control

Moscow, May 19-20, 2005

7

Extremality/Stationarity/Regularity



$$\theta[\Omega_1, \Omega_2](x^0) = 0$$

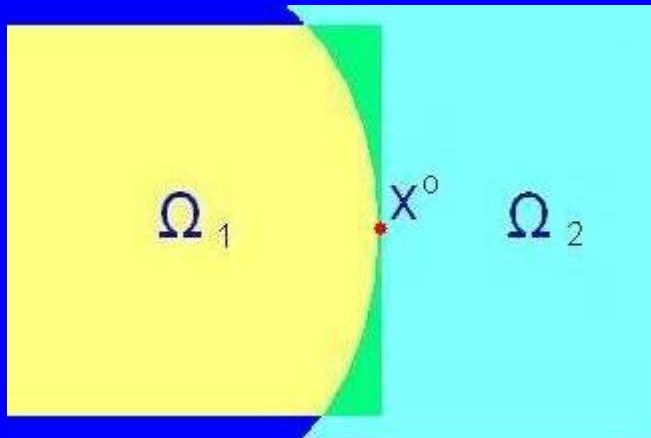


Optimization and Control

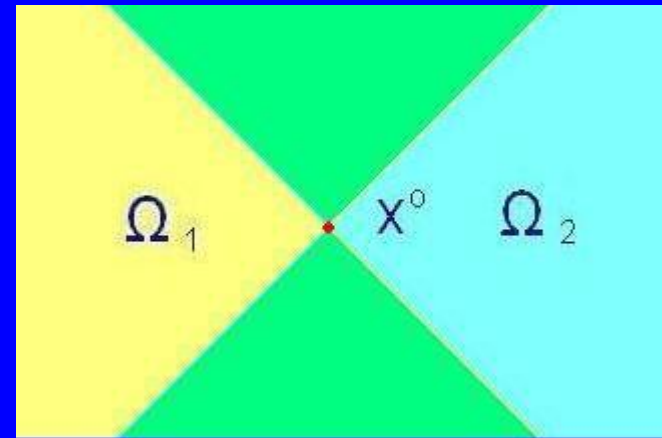
Moscow, May 19-20, 2005

7

Extremality/Stationarity/Regularity



$$\theta[\Omega_1, \Omega_2](x^0) = 0$$



$$\hat{\theta}[\Omega_1, \Omega_2](x^0) = 0$$



Optimization and Control

Moscow, May 19-20, 2005

8

Extremality/Stationarity/Regularity

Proposition 1. *Let $\Omega_1, \Omega_2, \dots, \Omega_n$ be **convex**. Then*

(1) \Leftrightarrow (2) \Leftrightarrow (3) \Leftrightarrow (4).



Optimization and Control

8

Moscow, May 19-20, 2005

Extremality/Stationarity/Regularity

Proposition 1. *Let $\Omega_1, \Omega_2, \dots, \Omega_n$ be **convex**. Then*

(1) \Leftrightarrow (2) \Leftrightarrow (3) \Leftrightarrow (4).

If $\text{int } \Omega_i \neq \emptyset$, $i = 1, 2, \dots, n - 1$, then these conditions are equivalent to

$$\bigcap_{i=1}^{n-1} \text{int } \Omega_i \cap \Omega_n = \emptyset.$$



Optimization and Control

9

Moscow, May 19-20, 2005

Dual Criteria

Fréchet normal cone to Ω at $x^\circ \in \Omega$

$$N(x^\circ | \Omega) = \left\{ x^* \in X^* : \limsup_{x \xrightarrow{\Omega} x^\circ} \frac{\langle x^*, x - x^\circ \rangle}{\|x - x^\circ\|} \leq 0 \right\}$$



Optimization and Control

Moscow, May 19-20, 2005

Dual Criteria

Fréchet normal cone to Ω at $x^\circ \in \Omega$

$$N(x^\circ | \Omega) = \left\{ x^* \in X^* : \limsup_{x \xrightarrow{\Omega} x^\circ} \frac{\langle x^*, x - x^\circ \rangle}{\|x - x^\circ\|} \leq 0 \right\}$$

$\Omega_1, \Omega_2, \dots, \Omega_n$ are closed, $x^\circ \in \bigcap_{i=1}^n \Omega_i$, $(0/0)_\infty = \infty$

$$\eta[\Omega_1, \dots, \Omega_n](x^\circ) = \liminf_{\delta \rightarrow +0} \left\{ \left(\left\| \sum_{i=1}^n x_i^* \right\| / \sum_{i=1}^n \|x_i^*\| \right)_\infty : \right. \\ \left. x_i^* \in N(x_i | \Omega_i), x_i \in \Omega_i \cap B_\delta(x^\circ), i = 1, \dots, n \right\}$$



Optimization and Control

10

Moscow, May 19-20, 2005

Dual Criteria

Theorem 1. $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) \leq \eta[\Omega_1, \dots, \Omega_n](x^\circ).$



Optimization and Control

10

Moscow, May 19-20, 2005

Dual Criteria

Theorem 1. $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) \leq \eta[\Omega_1, \dots, \Omega_n](x^\circ)$.

If X is *Asplund* and $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) < 1$ then

$$\eta[\Omega_1, \dots, \Omega_n](x^\circ) \leq \frac{\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}{1 - \hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}.$$



Optimization and Control

10

Moscow, May 19-20, 2005

Dual Criteria

Theorem 1. $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) \leq \eta[\Omega_1, \dots, \Omega_n](x^\circ)$.

If X is *Asplund* and $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) < 1$ then

$$\eta[\Omega_1, \dots, \Omega_n](x^\circ) \leq \frac{\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}{1 - \hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}.$$

Corollary 1.1. $\eta[\Omega_1, \dots, \Omega_n](x^\circ) = 0 \Rightarrow$

$\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is weakly stationary at x° .



Optimization and Control

10

Moscow, May 19-20, 2005

Dual Criteria

Theorem 1. $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) \leq \eta[\Omega_1, \dots, \Omega_n](x^\circ)$.

If X is *Asplund* and $\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ) < 1$ then

$$\eta[\Omega_1, \dots, \Omega_n](x^\circ) \leq \frac{\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}{1 - \hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)}.$$

Corollary 1.1. $\eta[\Omega_1, \dots, \Omega_n](x^\circ) = 0 \Rightarrow$

$\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is weakly stationary at x° .

If X is *Asplund* then the **Extended extremal principle** holds:

- $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is weakly stationary at $x^\circ \Leftrightarrow \eta[\Omega_1, \Omega_2, \dots, \Omega_n](x^\circ) = 0$.



Optimization and Control

11

Moscow, May 19-20, 2005

Dual Criteria

Extremal principle (Kruger, Mordukhovich, 1980;
Mordukhovich, Shao, 1996).

$\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is locally extremal at x°
 $\Rightarrow \eta[\Omega_1, \dots, \Omega_n](x^\circ) = 0.$



Optimization and Control

11

Moscow, May 19-20, 2005

Dual Criteria

Extremal principle (Kruger, Mordukhovich, 1980;
Mordukhovich, Shao, 1996).

$\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is locally extremal at x°
 $\Rightarrow \eta[\Omega_1, \dots, \Omega_n](x^\circ) = 0.$

Theorem 2. *The following assertions are equivalent:*

- *X is an Asplund space.*
- *The Extremal principle is valid in X .*
- *The Extended extremal principle is valid in X .*



Optimization and Control

12

Moscow, May 19-20, 2005

Metric Inequality

Ioffe, 1989; Bauschke, Borwein, 1993; Ngai, Théra, 2001.

$$(0/0)_{\circ} = 0$$

$$\vartheta[\Omega_1, \dots, \Omega_n](x^{\circ}) = \limsup_{x \rightarrow x^{\circ}} \left(\frac{d(x, \bigcap_{i=1}^n \Omega_i)}{\max_{1 \leq i \leq n} d(x, \Omega_i)} \right)_{\circ}$$



Optimization and Control

12

Moscow, May 19-20, 2005

Metric Inequality

Ioffe, 1989; Bauschke, Borwein, 1993; Ngai, Théra, 2001.

$$(0/0)_{\circ} = 0$$

$$\vartheta[\Omega_1, \dots, \Omega_n](x^{\circ}) = \limsup_{x \rightarrow x^{\circ}} \left(\frac{d(x, \bigcap_{i=1}^n \Omega_i)}{\max_{1 \leq i \leq n} d(x, \Omega_i)} \right)_{\circ}$$

$$\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^{\circ}) = \limsup_{\substack{x \rightarrow x^{\circ} \\ x_i \rightarrow 0}} \left(\frac{d(x, \bigcap_{i=1}^n (\Omega_i - x_i))}{\max_{1 \leq i \leq n} d(x + x_i, \Omega_i)} \right)_{\circ}$$



Optimization and Control

13

Moscow, May 19-20, 2005

Metric Inequality

Definition 2. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ satisfies at x°

- the *metric inequality* if $\vartheta[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.
- the *strong metric inequality* if $\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.



Optimization and Control

13

Moscow, May 19-20, 2005

Metric Inequality

Definition 2. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ satisfies at x°

- the *metric inequality* if $\vartheta[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.
- the *strong metric inequality* if $\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.

Theorem 3. $\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^\circ) = 1/\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)$.



Optimization and Control

13

Moscow, May 19-20, 2005

Metric Inequality

Definition 2. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ satisfies at x°

- the *metric inequality* if $\vartheta[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.
- the *strong metric inequality* if $\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^\circ) < \infty$.

Theorem 3. $\hat{\vartheta}[\Omega_1, \dots, \Omega_n](x^\circ) = 1/\hat{\theta}[\Omega_1, \dots, \Omega_n](x^\circ)$.

Corollary 3.1. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ is regular at x° if and only if it satisfies the strong metric inequality at x° .



Optimization and Control

14

Moscow, May 19-20, 2005

Boundary Condition

Borwein, Jofré, 1998

$\Omega_1, \Omega_2, \dots, \Omega_n$ are closed, $x_i^\circ \in \Omega_i, i = 1, 2, \dots, n$

$$\sum_{i=1}^n \Omega_i = \left\{ \omega = \sum_{i=1}^n \omega_i : \omega_i \in \Omega_i, i = 1, 2, \dots, n \right\}$$



Optimization and Control

14

Moscow, May 19-20, 2005

Boundary Condition

Borwein, Jofré, 1998

$\Omega_1, \Omega_2, \dots, \Omega_n$ are closed, $x_i^\circ \in \Omega_i, i = 1, 2, \dots, n$

$$\sum_{i=1}^n \Omega_i = \left\{ \omega = \sum_{i=1}^n \omega_i : \omega_i \in \Omega_i, i = 1, 2, \dots, n \right\}$$

$$\zeta_\rho[\Omega_1, \dots, \Omega_n](x_1^\circ, \dots, x_n^\circ) =$$

$$\sup \left\{ r \geq 0 : B_r\left(\sum_{i=1}^n x_i^\circ\right) \subset \sum_{i=1}^n (\Omega_i \cap B_\rho(x_i^\circ)) \right\}$$



Optimization and Control

15

Moscow, May 19-20, 2005

Boundary Condition

Definition 3. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ satisfies at $x_1^\circ, x_2^\circ, \dots, x_n^\circ$

- the *boundary condition* if

$$\zeta_\rho[\Omega_1, \dots, \Omega_n](x_1^\circ, \dots, x_n^\circ) = 0 \text{ for all } \rho > 0.$$

- the *local boundary condition* if

$$\zeta_\rho[\Omega_1, \dots, \Omega_n](x_1^\circ, \dots, x_n^\circ) = 0 \text{ for some } \rho > 0.$$



Optimization and Control

15

Moscow, May 19-20, 2005

Boundary Condition

Definition 3. $\{\Omega_1, \Omega_2, \dots, \Omega_n\}$ satisfies at $x_1^\circ, x_2^\circ, \dots, x_n^\circ$

- the *boundary condition* if

$$\zeta_\rho[\Omega_1, \dots, \Omega_n](x_1^\circ, \dots, x_n^\circ) = 0 \text{ for all } \rho > 0.$$

- the *local boundary condition* if

$$\zeta_\rho[\Omega_1, \dots, \Omega_n](x_1^\circ, \dots, x_n^\circ) = 0 \text{ for some } \rho > 0.$$

Proposition 2. Define $\tilde{x}^\circ = (x_1^\circ, x_2^\circ, \dots, x_n^\circ) \in X^n$, $\tilde{\Omega}_1 = \Omega_1 \times \dots \times \Omega_n$, $\tilde{\Omega}_2 = \{(x_1, \dots, x_n) \in X^n : \sum_{i=1}^n x_i = \sum_{i=1}^n x_i^\circ\}$. $\{\Omega_1, \dots, \Omega_n\}$ satisfies the (local) boundary condition at $x_1^\circ, \dots, x_n^\circ$ if and only if $\{\tilde{\Omega}_1, \tilde{\Omega}_2\}$ is (locally) extremal at \tilde{x}° .



Optimization and Control

16

Moscow, May 19-20, 2005

Regularity of Multifunctions

$F : X \Rightarrow Y$, $\text{gph } F = \{(x, y) \in X \times Y : y \in F(x)\}$,
 $(x^\circ, y^\circ) \in \text{gph } F$



Optimization and Control

16

Moscow, May 19-20, 2005

Regularity of Multifunctions

$F : X \Rightarrow Y$, $\text{gph } F = \{(x, y) \in X \times Y : y \in F(x)\}$,
 $(x^\circ, y^\circ) \in \text{gph } F$

$$\theta_\rho[F](x^\circ, y^\circ) = \sup\{r \geq 0 : B_r(y^\circ) \subset F(B_\rho(x^\circ))\}$$



Optimization and Control

16

Moscow, May 19-20, 2005

Regularity of Multifunctions

$F : X \Rightarrow Y$, $\text{gph } F = \{(x, y) \in X \times Y : y \in F(x)\}$,
 $(x^\circ, y^\circ) \in \text{gph } F$

$$\theta_\rho[F](x^\circ, y^\circ) = \sup\{r \geq 0 : B_r(y^\circ) \subset F(B_\rho(x^\circ))\}$$

$$\theta[F](x^\circ, y^\circ) = \liminf_{\rho \rightarrow +0} \frac{\theta_\rho[F](x^\circ, y^\circ)}{\rho}$$



Optimization and Control

16

Moscow, May 19-20, 2005

Regularity of Multifunctions

$F : X \Rightarrow Y$, $\text{gph } F = \{(x, y) \in X \times Y : y \in F(x)\}$,
 $(x^\circ, y^\circ) \in \text{gph } F$

$$\theta_\rho[F](x^\circ, y^\circ) = \sup\{r \geq 0 : B_r(y^\circ) \subset F(B_\rho(x^\circ))\}$$

$$\theta[F](x^\circ, y^\circ) = \liminf_{\rho \rightarrow +0} \frac{\theta_\rho[F](x^\circ, y^\circ)}{\rho}$$

$$\hat{\theta}[F](x^\circ, y^\circ) = \liminf_{(x, y) \xrightarrow{\text{gph } F} (x^\circ, y^\circ)} \theta[F](x, y)$$



Optimization and Control

17

Moscow, May 19-20, 2005

Regularity of Multifunctions

Definition 4. $F : X \Rightarrow Y$ is

- (1) *extremal* at (x°, y°) if $\theta_\rho[F](x^\circ, y^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at (x°, y°) if $\theta_\rho[F](x^\circ, y^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at (x°, y°) if $\theta[F](x^\circ, y^\circ) = 0$.
- (4) *weakly stationary* at (x°, y°) if $\hat{\theta}[F](x^\circ, y^\circ) = 0$.
- (5) *regular* at (x°, y°) if $\hat{\theta}[F](x^\circ, y^\circ) > 0$.



Optimization and Control

17

Moscow, May 19-20, 2005

Regularity of Multifunctions

Definition 4. $F : X \Rightarrow Y$ is

- (1) *extremal* at (x°, y°) if $\theta_\rho[F](x^\circ, y^\circ) = 0$ for all $\rho > 0$.
- (2) *locally extremal* at (x°, y°) if $\theta_\rho[F](x^\circ, y^\circ) = 0$ for some $\rho > 0$.
- (3) *stationary* at (x°, y°) if $\theta[F](x^\circ, y^\circ) = 0$.
- (4) *weakly stationary* at (x°, y°) if $\hat{\theta}[F](x^\circ, y^\circ) = 0$.
- (5) *regular* at (x°, y°) if $\hat{\theta}[F](x^\circ, y^\circ) > 0$.

(5) $\Leftrightarrow F$ is *metrically regular* at (x°, y°)



Optimization and Control

18

Moscow, May 19-20, 2005

Regularity of Multifunctions

Theorem 4. Define $\Omega_1 = \text{gph}(F)$, $\Omega_2 = X \times \{y^\circ\}$. The following assertions hold:

- F is extremal at $(x^\circ, y^\circ) \Leftrightarrow \{\Omega_1, \Omega_2\}$ is extremal at (x°, y°) .
- F is locally extremal at $(x^\circ, y^\circ) \Leftrightarrow \{\Omega_1, \Omega_2\}$ is locally extremal at (x°, y°) .
- F is stationary at $(x^\circ, y^\circ) \Leftrightarrow \{\Omega_1, \Omega_2\}$ is stationary at (x°, y°) .
- F is weakly stationary at $(x^\circ, y^\circ) \Leftrightarrow \{\Omega_1, \Omega_2\}$ is weakly stationary at (x°, y°) .
- F is regular at $(x^\circ, y^\circ) \Leftrightarrow \{\Omega_1, \Omega_2\}$ is regular at (x°, y°) .



Optimization and Control

19

Moscow, May 19-20, 2005

References

- J. M. Borwein and A. Jofré, *A nonconvex separation property in Banach spaces*, Math. Meth. Oper. Res. **48** (1998), 169–179.
- A. D. Ioffe, *Approximate subdifferentials and applications. 3: the metric theory*, Mathematika **36** (1989), 1–38.
- A. Y. Kruger, *Weak stationarity: eliminating the gap between necessary and sufficient conditions*, Optimization **53** (2004), 147–164.



Optimization and Control

20

Moscow, May 19-20, 2005

- A. Y. Kruger, *Stationarity and regularity of set systems*, *Pacif. J. Optimiz.* **1** (2005), 101–126.
- A. Y. Kruger and B. S. Mordukhovich, *Extremal points and the Euler equation in nonsmooth optimization*, *Dokl. Akad. Nauk BSSR* **24:8** (1980), 684–687, in Russian.
- B. S. Mordukhovich and Y. Shao, *Extremal characterizations of Asplund spaces*, *Proc. Amer. Math. Soc.* **124** (1996), 197–205.
- H. Ngai and M. Théra, *Metric inequality, subdifferential*



Optimization and Control

21

Moscow, May 19-20, 2005

calculus and applications, Set-Valued Analysis **9** (2001),
187–216.